

**PROBLEM SET 3 – DUE: JANUARY 31, 2006**

**Instructions**

Please try to answer the questions rigorously by stating any implied assumptions and ensuring all the steps to your conclusion have been properly verified.

**Part I – Analytical Questions**

1. Suppose  $\hat{\pi}_T \xrightarrow{p} \pi_0$  and let  $g(\hat{\pi}_T; \theta) = \hat{\pi}_T - h(\theta)$ , where  $h$  is a continuous function and where  $V(\hat{\pi}_T) = \sigma^2$ .

(a) Show that

$$\sqrt{T}(\hat{\theta}_T - \theta_0) \xrightarrow{d} N\left(0, (G'WG)^{-1}G'W\sigma^2WG(G'WG)^{-1}\right)$$

where  $G = \nabla_{\theta}g(\hat{\pi}_T; \theta)$  and find the specific version of this expression that applies to this problem with optimal weighting matrix  $W = (\sigma^2)^{-1}$ .

(b) Suppose  $h(\theta) = 3\theta^2$ . Derive the asymptotic distribution for this particular case.

(c) Instead, use the delta method to derive the asymptotic distribution of  $\hat{\theta}_T$  in (b). Verify that you get the same results with both methods.

2. Suppose  $y_t = \mu + \varepsilon_t + \theta\varepsilon_{t-1}$ . Define  $Y = (y_1, \dots, y_T)'$ ; and  $M = (\mu, \dots, \mu)'$ .

(a) Obtain  $\Omega = E(Y - M)(Y - M)'$

(b) Hence derive the log-likelihood function for  $Y$ .

(c) Show that the log-likelihood for  $Y$  is equivalent to the log-likelihood based on

$$\frac{1}{T} \sum \ln f(y_t; \theta)$$

3. The Hannan-Rissanen estimator for an MA(1) is a two step estimator in which the first step, a long autoregression is fitted to the data and in the second step, the residuals of the first step are used as regressors in the MA(1) specification. Suppose the D.G.P. is

$$y_t = \varepsilon_t + \theta\varepsilon_{t-1}; \quad |\theta| < 1$$

(a) The first step in the Hannan-Rissanen method consists of estimating

$$y_t = \rho_1 y_{t-1} + \dots + \rho_p y_{t-p} + u_t$$

where  $p$  is fixed (for example, chosen by information criteria). Assuming  $\hat{\rho}_j \xrightarrow{p} \theta^j$  for  $j = 1, \dots, p$ , derive the expression for  $\hat{u}_t$  and show under what conditions  $\hat{u}_t \xrightarrow{p} \varepsilon_t$ .

(b) The second step consists in estimating  $\theta$  with the regression

$$y_t = v_t + \theta \hat{u}_t$$

Show that this estimator is consistent for  $\hat{\theta}$ .

(c) Derive the asymptotic distribution of  $\hat{\theta}$ . Show that this estimator is less efficient than the maximum likelihood estimator.

4. Consider the following ARMA(2,1) model

$$y_t = 2 + 1.2y_{t-1} - 0.5y_{t-2} + \varepsilon_t + 0.25\varepsilon_{t-1}$$

(a) Write this model in state-space form

(b) Using this form, verify whether the model is covariance stationary (you may use GAUSS).

(c) Compute the expression for  $E(y_{t+2} | y_{t-1}, \dots)$

(d) Derive the infinite MA representation for this model.

### COMPUTER PROBLEM

Coming soon under separate cover.