

# Analysis of Economics Data

## Appendix C: Properties of OLS, IV and ML

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# APPENDIX C: Properties of OLS, IV and ML

- Appendix C considers properties of OLS and related estimator.
- C.1 OLS with Independent Homoskedastic Errors
- C.2 Robust Standard errors
- C.3 Instrumental Variables Estimation
- C.4 OLS with Matrix Algebra
- C.5 Maximum Likelihood Estimation

## C.1: OLS with Independent Homoskedastic Errors

- Simplify model to make algebra easier by dropping intercept

$$y_i = \beta x + u_i.$$

- Then OLS estimator is

$$b = (\sum_i x_i^2)^{-1} \sum_i x_i y_i.$$

- Also simplify by assume  $x_i$  is a fixed regressor. Then assume.
- 1 Model:  $y_i = \beta x_i + u_i$ .
  - 2 Zero error mean:  $E[u_i] = 0$ .
  - 3 Constant error variance:  $\text{Var}[u_i] = \sigma_u^2$ .
  - 4 Uncorrelated errors:  $\text{Cov}[u_i, u_j] = 0, \quad i \neq j$ .

## A key result

- Given assumption 1 it is always the case that

$$b = \beta + (\sum_i x_i^2)^{-1} (\sum_i x_i u_i).$$

- To obtain this result, note that

$$\begin{aligned} b &= (\sum_i x_i^2)^{-1} (\sum_i x_i y_i) \\ &= (\sum_i x_i^2)^{-1} (\sum_i x_i (\beta x_i + u_i)) && \text{assuming } y_i = \beta x_i + u_i. \\ &= (\sum_i x_i^2)^{-1} (\sum_i \beta x_i^2 + \sum_i x_i u_i) \\ &= (\sum_i x_i^2)^{-1} (\sum_i \beta x_i^2) + (\sum_i x_i^2)^{-1} (\sum_i x_i u_i) \\ &= \beta + (\sum_i x_i^2)^{-1} (\sum_i x_i u_i), \end{aligned}$$

- The mean and variance of  $b$  will depend on assumptions about  $u_i$ .

## Mean of the OLS Estimator

- Since  $b = \beta + (\sum_i x_i^2)^{-1}(\sum_i x_i u_i)$  we have

$$\begin{aligned}
 E[b] &= E[\beta + (\sum_i x_i^2)^{-1}(\sum_i x_i u_i)] \\
 &= E[\beta] + E[(\sum_i x_i^2)^{-1}(\sum_i x_i u_i)] \\
 &= \beta + (\sum_i x_i^2)^{-1} \times E[\sum_i x_i u_i] \\
 &= \beta + (\sum_i x_i^2)^{-1} \times \sum_i E[x_i u_i] \\
 &= \beta \quad \text{if } E[x_i u_i] = 0.
 \end{aligned}$$

- $E[x_i u_i] = 0$  given assumption 2 that  $E[u_i] = 0$ 
  - ▶ since  $x_i$  is fixed so  $E[x_i u_i] = x_i E[u_i] = x_i \times 0 = 0$  assuming  $E[u_i] = 0$ .

## Variance of OLS with Independent Homoskedastic Errors

- Since  $b = \beta + (\sum_i x_i^2)^{-1} (\sum_i x_i u_i)$   
the variance of  $b$  is simply the variance of  $(\sum_i x_i^2)^{-1} (\sum_i x_i u_i)$ .
- Given independent and homoskedastic errors and fixed  $x_i$

$$\begin{aligned}
 \text{Var}[b] &= \text{Var}[(\sum_i x_i^2)^{-1} (\sum_i x_i u_i)] \\
 &= \{(\sum_i x_i^2)^{-1}\}^2 \times \text{Var}[\sum_i x_i u_i] \quad \text{as } \text{Var}[aY] = a^2 \text{Var}[Y] \\
 &= (\sum_i x_i^2)^{-2} \times \sum_i \text{Var}[x_i u_i] \quad \text{by independence} \\
 &= (\sum_i x_i^2)^{-2} \times \sum_i x_i^2 \text{Var}[u_i] \quad \text{as fixed } x_i \\
 &= (\sum_i x_i^2)^{-2} \times \sum_i x_i^2 \times \sigma_u^2 \quad \text{for homoskedastic errors.} \\
 &= \sigma_u^2 (\sum_i x_i^2)^{-1} \quad \text{simplifying.}
 \end{aligned}$$

- We estimate  $\sigma_u^2$  using  $s_e^2 = \frac{1}{n-1} \sum_i e_i^2$  where  $e_i = y_i - \hat{y}_i$ . Then

$$\text{Estimated Var}[b] = \frac{s_e^2}{\sum_i x_i^2}.$$

- With an intercept  $\widehat{\text{Var}}[b] = \frac{s_e^2}{\sum_i (x_i - \bar{x})^2}$  where  $s_e^2 = \frac{1}{n-2} \sum_i e_i^2$ .

## C.2 Robust Standard Errors Summary

- Since  $b = \beta + (\sum_i x_i^2)^{-1} (\sum_i x_i u_i)$  some algebra yields

$$\begin{aligned} \text{Var}[b] &= (\sum_i x_i^2)^{-2} \times \text{Var} [\sum_i x_i u_i] \\ &= (\sum_i x_i^2)^{-2} \times \sum_i \text{Var} [x_i u_i] && \text{if errors are independent} \\ &= (\sum_i x_i^2)^{-2} \times \sum_i \sum_j x_i x_j E[u_i u_j] && \text{in general.} \end{aligned}$$

- This leads to robust standard error estimates where  $e_i = y_i - \hat{y}_i$ .
- Heteroskedastic independent errors

$$\widehat{\text{Var}}_{het}[b] = (\sum_i x_i^2)^{-2} \sum_i x_i^2 e_i^2.$$

- Clustered (and heteroskedastic errors) where  $\delta_{ij} = 1$  if  $i$  and  $j$  in same cluster

$$\widehat{\text{Var}}_{clu}[b] = (\sum_i x_i^2)^{-2} \times \sum_i \sum_j \delta_{ij} x_i x_j e_i e_j.$$

- Autocorrelated errors (to  $m$  periods apart)

$$\begin{aligned} \widehat{\text{Var}}_{HAC}[b] &= (\sum_t x_t^2)^{-2} \times \left\{ \sum_{t=1}^T x_t^2 e_t^2 + \frac{2m}{m+1} \sum_{t=2}^m x_t x_{t-1} e_t e_{t-1} \right. \\ &\quad \left. + \dots + \frac{2}{m+1} \sum_{t=m}^T x_t x_{t-m} e_t e_{t-m} \right\}, \end{aligned}$$

## Robust Standard Errors Algebra

- Since  $b = \beta + (\sum_i x_i^2)^{-1}(\sum_i x_i u_i)$

the variance of  $b$  is simply the variance of  $(\sum_i x_i^2)^{-1}(\sum_i x_i u_i)$ .

$$\begin{aligned}\text{Var}[b] &= \text{Var} \left[ \left\{ (\sum_i x_i^2)^{-1} \sum_i x_i u_i \right\} \right] \\ &= \left\{ (\sum_i x_i^2)^{-1} \right\}^2 \times \text{Var} [\sum_i x_i u_i] \\ &= (\sum_i x_i^2)^{-2} \times \text{Var} [\sum_i x_i u_i]\end{aligned}$$

- In general  $\text{Var}[\sum_{i=1}^n Y_i] = \sum_i \sum_j \text{Cov}[Y_i, Y_j]$ . So

$$\begin{aligned}\text{Var} [\sum_i x_i u_i] &= \sum_i \sum_j \text{Cov}[x_i u_i, x_j u_j] \\ &= \sum_i \sum_j x_i x_j \text{Cov}[u_i, u_j] \\ &= \sum_i \sum_j x_i x_j \text{E}[u_i u_j] \text{ using } \text{E}[u_i] = 0.\end{aligned}$$

- So

$$\begin{aligned}\text{Var}[b] &= (\sum_i x_i^2)^{-2} \times \text{Var} [\sum_i x_i u_i] \\ &= (\sum_i x_i^2)^{-2} \times \sum_i \sum_j x_i x_j \text{E}[u_i u_j] \quad \text{in general.}\end{aligned}$$



## Variance with Heteroskedastic Independent Errors

- Given independent and heteroskedastic errors and fixed  $x_i$

$$\begin{aligned} E[u_i u_j] &= E[u_i^2] \text{ if } i = j \\ &= 0 \text{ if } i \neq j. \end{aligned}$$

- Then

$$\begin{aligned} \text{Var}[b] &= (\sum_i x_i^2)^{-2} \times \sum_i \sum_j x_i x_j E[u_i u_j] && \text{in general} \\ &= (\sum_i x_i^2)^{-2} \times \sum_i x_i^2 E[u_i^2]. \end{aligned}$$

- We estimate  $\sum_i x_i^2 E[u_i^2]$  using  $\sum_i x_i^2 e_i^2$ . Then

$$\widehat{\text{Var}}_{het}[b] = \frac{\sum_i x_i^2 e_i^2}{(\sum_i x_i^2)^2}.$$

## Variance with Clustered Errors

- Define

$\delta_{ij} = 1$  if observations  $i$  and  $j$  are in the same cluster

$\delta_{ij} = 0$  otherwise.

- Then with clustered errors we assume

$$\text{Cov}[u_i, u_j] = E[u_i, u_j] \neq 0 \text{ if } \delta_{ij} = 1$$

$$\text{Cov}[u_i, u_j] = 0 \text{ if } \delta_{ij} = 0$$

- So given clustered (and heteroskedastic) errors and fixed  $x_i$

$$\begin{aligned} \text{Var}[b] &= (\sum_i x_i^2)^{-2} \times \sum_i \sum_j x_i x_j E[u_i u_j] && \text{in general} \\ &= (\sum_i x_i^2)^{-2} \times \sum_i \sum_j \delta_{ij} x_i x_j E[u_i u_j]. \end{aligned}$$

- We estimate  $\sum_i \sum_j \delta_{ij} x_i x_j E[u_i u_j]$  by  $\sum_i \sum_j \delta_{ij} x_i x_j e_i e_j$ .

$$\widehat{\text{Var}}_{clu}[b] = \frac{\sum_i \sum_j \delta_{ij} x_i x_j e_i e_j}{(\sum_i x_i^2)^2}.$$

## Variance with Autocorrelated Errors

- Use subscript  $t$  for time series (rather than subscript  $i$ ).
- Assume that errors are uncorrelated after  $m$  periods

$$\begin{aligned} \text{Cov}[u_t, u_s] &\neq 0 \text{ for } |t - s| \leq m \\ &= 0 \text{ for } |t - s| > m, \end{aligned}$$

- Then

$$\begin{aligned} \text{Var}[\sum_t x_t u_t] &= \sum_t \sum_t x_t x_s E[x_t u_t u_t u_s] \quad \text{in general} \\ &= \sum_t E[x_t u_t] + 2 \sum_t E[x_t u_t x_{t-1} u_{t-1}] \\ &\quad + \cdots + 2 \sum_t E[x_t u_t, x_{t-m} u_{t-m}] \text{ as correlated up to } m \text{ periods} \end{aligned}$$

- We estimate  $\text{Var}[b] = (\sum_t x_t^2)^{-2} \times \text{Var}[\sum_t x_t u_t]$  with

$$\begin{aligned} \widehat{\text{Var}}_{HAC}[b] &= (\sum_t x_t^2)^{-1} \times \left\{ \sum_{t=1}^T x_t^2 \hat{u}_t^2 + \frac{2m}{m+1} \sum_{t=2}^m x_t x_{t-1} \hat{u}_t \hat{u}_{t-1} \right. \\ &\quad \left. + \cdots + \frac{2}{m+1} \sum_{t=m}^T x_t x_{t-m} \hat{u}_t \hat{u}_{t-m} \right\} \times (\sum_t x_t^2)^{-1}, \end{aligned}$$

## C.3 Instrumental Variables

- Consider model without intercept:  $y_i = \beta x_i + u_i$ .
- Suppose  $\text{Cov}(x_i, u_i) \neq 0$ . Then **OLS is biased and inconsistent** as

$$\begin{aligned} E[b] &= \beta + (\sum_i x_i^2)^{-1} \times \sum_i E[x_i u_i] && \text{from earlier OLS results} \\ &\neq \beta && \text{because } E[x_i u_i] \neq 0. \end{aligned}$$

- Instead **assume there exists an instrument  $z_i$  that is uncorrelated with the error**. Specifically  $\text{Cov}(z_i, u_i) = 0$  which implies the average  $(\frac{1}{n} \sum_i z_i u_i) \rightarrow 0$  as  $n \rightarrow \infty$ .
- The instrumental variables estimator of  $\beta$  is

$$b_{IV} = (\sum_{i=1}^n z_i x_i)^{-1} \sum_{i=1}^n z_i y_i.$$

- The instrumental variables estimator is **consistent** for  $\beta$  since

$$\begin{aligned} b_{IV} &= \beta + (\sum_i z_i x_i)^{-1} (\sum_i z_i u_i) && \text{by algebra similar to OLS} \\ &= \beta + (\frac{1}{n} \sum_i z_i x_i)^{-1} (\frac{1}{n} \sum_i z_i u_i) \\ &\rightarrow \beta + (\frac{1}{n} \sum_i z_i x_i)^{-1} \times 0 \text{ as } n \rightarrow \infty \text{ as } \text{Cov}(z_i, u_i) = 0 \\ &\rightarrow \beta. \end{aligned}$$

## C.4 OLS with Matrix Algebra

- Let  $y_i = \beta_1 + \beta_2 x_{2i} + \beta_3 x_{3i} + \cdots + \beta_k x_{ki} + u_i$ .
- In vector notation this can be written as

$$y_i = \begin{bmatrix} 1 & x_{2i} & \cdots & x_{ki} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} + u_i.$$

- Stacking all  $n$  equations for the  $n$  observations into vectors and matrices yields

$$\begin{bmatrix} y_1 \\ \vdots \\ y_i \\ \vdots \\ y_n \end{bmatrix} = \begin{bmatrix} 1 & x_{21} & \cdots & x_{k1} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{2i} & \cdots & x_{ki} \\ \vdots & \vdots & \vdots & \vdots \\ 1 & x_{2n} & \cdots & x_{kn} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \\ \vdots \\ \beta_k \end{bmatrix} + \begin{bmatrix} u_1 \\ \vdots \\ u_i \\ \vdots \\ u_n \end{bmatrix}.$$

## OLS with Matrix Algebra (continued)

- The stacked model can be written as

$$\mathbf{y} = \mathbf{X}\boldsymbol{\beta} + \mathbf{u},$$

$(n \times 1)$        $(n \times k)$   $(k \times 1)$        $(n \times 1)$

for  $n \times 1$  vectors  $\mathbf{y}$  and  $\mathbf{u}$ ,  $n \times k$  matrix  $\mathbf{X}$ , and  $k \times 1$  vector  $\boldsymbol{\beta}$ .

- The OLS estimator that minimizes the sum of squared residuals  $\mathbf{u}'\mathbf{u}$  solves the so-called normal equations  $\mathbf{X}'\mathbf{u} = \mathbf{0}$  or

$$\mathbf{X}'(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}) = \mathbf{0}.$$

- Solving for  $\boldsymbol{\beta}$  yields the the OLS estimator:

$$\mathbf{b} = (\mathbf{X}'\mathbf{X})^{-1}\mathbf{X}'\mathbf{y},$$

where  $\mathbf{b}$  is a  $k \times 1$  vector with entries  $b_1, b_2, \dots, b_k$ .

- Under assumptions 1-4

$$\text{Var}[\mathbf{b}] = \sigma_u^2(\mathbf{X}'\mathbf{X})^{-1} \text{ and } \widehat{\text{Var}}[\mathbf{b}] = s_e^2(\mathbf{X}'\mathbf{X})^{-1}$$

where  $s_e^2 = \frac{1}{n-k} \sum_{i=1}^n \hat{u}_i^2 = \frac{1}{n-k} \hat{\mathbf{u}}'\hat{\mathbf{u}}$  where  $\hat{\mathbf{u}} = \mathbf{y} - \mathbf{X}\mathbf{b}$ .

## C.5 Maximum Likelihood Estimation

- For some types of data OLS is not appropriate.
- Then the **maximum likelihood (ML) method is often used**.
- This specifies a particular model for the conditional probability of the dependent variable given the regressors.
- Let  $f(y_i|x_i, \theta)$  denote the model for the  $i$ th observation.
- The probability of observing the  $n$  independent observations is then

$$f(y_1, \dots, y_n|x_1, \dots, x_n, \theta) = f(y_1|x_1, \theta) \times \dots \times f(y_n|x_n, \theta).$$

- The **likelihood function** reframes this probability as a function of the parameter(s)  $\theta$  given the data  $(y_1, x_1), \dots, (y_n, x_n)$ . Then

$$L(\theta) = L(\theta|(y_1, x_1), \dots, (y_n, x_n)) = f(y_1|x_1, \theta) \times \dots \times f(y_n|x_n, \theta).$$

- We estimate  $\theta$  by the value that is most likely given the data; i.e. the **maximum likelihood estimator** maximizes  $L(\theta)$ .
- Equivalently use  $\theta$  that maximizes the natural logarithm of  $L(\theta)$

$$\ln L(\theta) = \ln f(y_1|x_1, \theta) + \dots + \ln f(y_n|x_n, \theta) = \sum_{i=1}^n \ln f(y_i|x_i, \theta).$$

## Maximum Likelihood Estimation Properties

- The **maximum likelihood estimator** (MLE) of  $\theta$ , denoted  $\hat{\theta}_{ML}$ , maximizes  $\ln L(\theta) = \sum_{i=1}^n \ln f(y_i|x_i, \theta)$ .
- For standard problems the MLE has very desirable properties.
- Assuming  $f(y_i|x_i, \theta)$  is correctly specified the MLE is consistent, has asymptotic distribution that is normal, and has the smallest variance among consistent and asymptotically normal estimators.
- If inference is relaxed to allow for the possibility that  $f(y_i|x_i, \theta)$  is incorrectly specified then the MLE is called the **quasi-MLE**. Then inference must be based on appropriate robust standard errors.
- In general the quasi-MLE is inconsistent for  $\theta$ , though in the leading cases of logit, probit and Poisson regression, and the linear model with independent normally distributed errors, the quasi-MLE is still consistent for  $\theta$  provided that the functional form for the conditional mean  $E[y_i|x_i]$  is correctly specified.



## Maximum Likelihood Estimation Example

- Consider regression where  $y_i$  is a binary outcome with probability

$$f(y_i | p_i) = \begin{cases} p_i & \text{if } y_i = 1 \\ 1 - p_i & \text{if } y_i = 0 \end{cases}$$

- This can be rewritten as

$$f(y_i | p_i) = p_i^{y_i} (1 - p_i)^{1 - y_i}.$$

- The logit regression model specifies

$$p_i = \Lambda(\beta_1 + \beta_2 x_i) = \exp(\beta_1 + \beta_2 x_i) / \{1 + \exp(\beta_1 + \beta_2 x_i)\}.$$

- The log-likelihood function given independent observations is then

$$\begin{aligned} \ln L(\beta_1, \beta_2) &= \prod_{i=1}^n p_i^{y_i} (1 - p_i)^{1 - y_i} \\ &= \sum_{i=1}^n \{y_i \ln p_i + (1 - y_i) \ln(1 - p_i)\} \\ &= \sum_{i=1}^n \{y_i \ln \Lambda(\beta_1 + \beta_2 x_i) + (1 - y_i) \ln(1 - \Lambda(\beta_1 + \beta_2 x_i))\} \end{aligned}$$

- The ML estimates of  $\beta_1$  and  $\beta_2$  maximize this function.